

Policy Division and Fusion: Examples and A Method

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This presentation consists of:

1. Introduction to policy division and fusion
2. Examples and problems in Diffserv
3. A Method of policy division and fusion
4. Resolution of the problems



1. Introduction to policy division and fusion

Introduction

■ In a policy-based network

- ◆ A policy server deploys policies to network nodes.
- ◆ Policies may work in cooperation.
 - E.g., in Diffserv, marking and queuing/scheduling policies — the latter depend on the former.

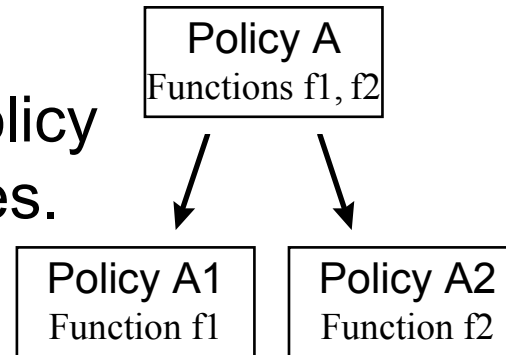
■ Higher-level (HL) and lower-level (LL) policies

- ◆ A “Policy” means a list of condition-action rules.
- ◆ Both a policy server and network nodes work with policies.
 - LL commands for a network interface (e.g., ACLs) form a *LL policy*.
 - A policy server has *HL policies*.
- ◆ HL policies must be translated into LL policies.
 - This translation is similar to compilation of programming languages such as C/C++.
 - This process is much more complex; the correspondence between HL and LL policies is not one-to-one.

What are policy division and fusion?

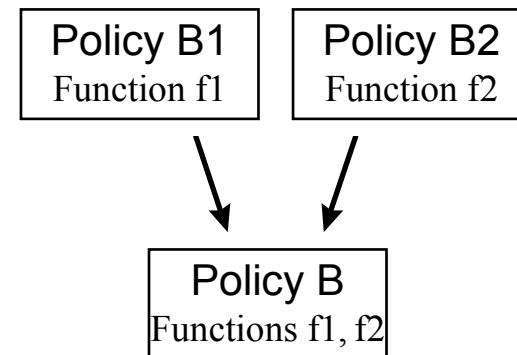
■ Policy division

- ◆ Transformation of a HL policy into two or more LL policies.

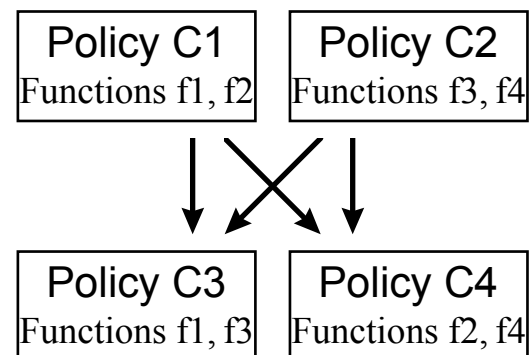


■ Policy fusion

- ◆ Transformation of two or more HL policies into a LL policy.



■ A combination of policy division and fusion:



Simple policy division

◆ Input: a HL policy P

- $P = \{ \dots, \text{if } (C_i) \{ A_{i1}; \dots; A_{in}; \}, \dots \}$

— a rule with n actions (various types of actions in a policy).

◆ Outputs: LL policies P_1, \dots, P_n

- $P_1 = \{ \dots, \text{if } (C_i) \{ A_{i1}; \}, \dots \},$

— limited types of actions in a policy.

.....
■ $P_n = \{ \dots, \text{if } (C_i) \{ A_{in}; \}, \dots \}.$

◆ Notes

- Every rule in P is divided into n rules.

- The number of rules in P, P_1, \dots, P_n are the same.

Simple policy fusion (Case 1)

◆ **Inputs:** HL policies P_1, \dots, P_n

■ $P_1 = \{ \dots, \text{if } (C_i) \{ A_{i1}; \}, \dots \},$

...

$P_n = \{ \dots, \text{if } (C_i) \{ A_{in}; \}, \dots \}.$

◆ **Output:** a LL policy P

■ $P = \{ \dots, \text{if } (C_i) \{ A_{i1}; \dots; A_{in}; \}, \dots \}$ — a rule with n actions

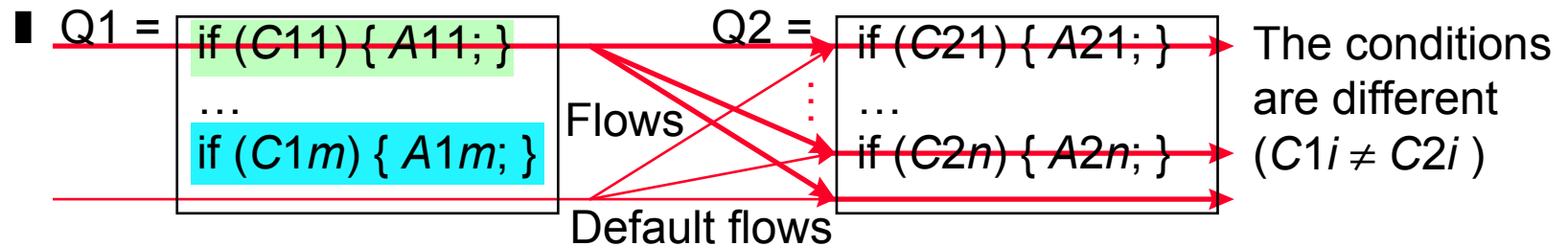
◆ **Note**

■ The number of rules in P_1, \dots, P_n , and P are the same.

■ i -th rules of P_1, \dots, P_n have the same condition C_i — a very rare case.

Simple policy fusion (Case 2)

◆ Inputs: HL policies Q1 and Q2



◆ Output: a LL policy Q

■ Q = { `if (C11 AND C21) { A11; A21; },`
 ...,
`if (C11 AND C2n) { A11; A2n; },`
`if (C11) { A11; },` — $n+1$ rules

...,
`if (C1m AND C21) { A1m; A21; },`
 ...,
`if (C1m AND C2n) { A1m; A2n; },`
`if (C1m) { A1m; },` — $n+1$ rules

`if (C21) { A21; },`
 ...,
`if (C2n) { A2n; } }.`

The number of rules in Q:
 $(m+1)(n+1) - 1$ — *too many!!*

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2. Examples and problems in Diffserv

Example policy types for Diffserv

■ Definition of HL policy types

◆ Edge policy

- A type of policy that *classifies*, *meters*, and/or *marks* packets.
- E.g., if (Source_IP == 192.168.0.1) {
 if (Information_rate < 1M bps) { DSCP = 46; } else { drop; };
}

◆ Core policy

- A type of policy that *queues*, *schedules*, and *randomly drops* packets.
- E.g., if (DSCP == 46) {
 Queue_number = 6;
 Scheduling_algorithm = "Priority_scheduling";
}

Example policy types for Diffserv (cont'd)

- Each LL policy type may correspond to a command.

- **Definition of LL policy types**

- ◆ Filtering policy

- A type of policy that *classifies*, *filters*, and/or *marks* a DSCP on packets.
- E.g., `if (Source_IP == 192.168.0.1) { DSCP = 46; }`,

- ◆ Metering and scheduling policy

- A type of policy that *meters*, *queues*, and/or *schedules* packets.
- E.g., `if (DSCP == 46) {
 if (Information_rate < 1M bps) {
 Queue_number = 6;
 Scheduling_algorithm = "Priority_scheduling";
 } else {
 drop; }; }.`

- **A restriction on the LL policies**

- ◆ The conditions may not contain “OR” (flow aggregation).
 - `if (... OR ...) { ... }` — not allowed (must be divided into two rules)

Why are policy division/fusion required?

- **Because the functional correspondence between HL and LL policies is not one-to-one.**
 - ◆ E.g., Policy A has function f1 and f2, but policy A1 only has f1 and policy A2 only has f2.
- **Because of functional restrictions of the network nodes.**
 - ◆ Policy servers should implement HL policies that are standardized and device-independent.
 - ◆ LL policies may be restrictive because they may be implemented in hardware, or high performance is required.
 - The LL policies and the policy division/fusion are implemented in the PolicyXpert agent for Hitachi's gigabit router GR2000.

Policy division example 1: with metering

◆ This example is similar to the simple one given before.

◆ **Input:** edge policy E

```
■ E = { ...,  
  if (Source_IP == ai) {  
    if (Information_rate < 1M bps) { DSCP = di; } else { drop; }; },  
  ...  
}.
```

Metering action (points to `Information_rate < 1M bps`)
Marking action (points to `DSCP = di;`)

◆ **Outputs:** filtering policy F and metering and scheduling policy MS

```
■ F = { ...,  
  if (Source_IP == ai) { DSCP = di; },  
  ...  
},
```

Marking action (points to `DSCP = di;`)

```
■ MS = { ...,  
  if (Source_IP == ai) {  
    if (Information_rate < 1M bps) {} else { drop; }; },  
  ...  
}.
```

Metering action (points to `Information_rate < 1M bps`)

Policy division example 2: with aggregation

◆ Input: edge policy E'

■ E' =

```
{ if ( Source_IP == a1 OR
    ... OR
    Source_IP == an ) {           — The flows are aggregated here.
    if (Information_rate < 1M bps) { DSCP = 10; } else { drop; }; }
}
```

◆ Outputs: filtering policy F' and metering and scheduling policy MS'

■ F' = { if (Source_IP == a1) { DSCP = 10; },
 ...,
 if (Source_IP == an) { DSCP = 10; } }.

— The flows are aggregated by marking DSCP 10.

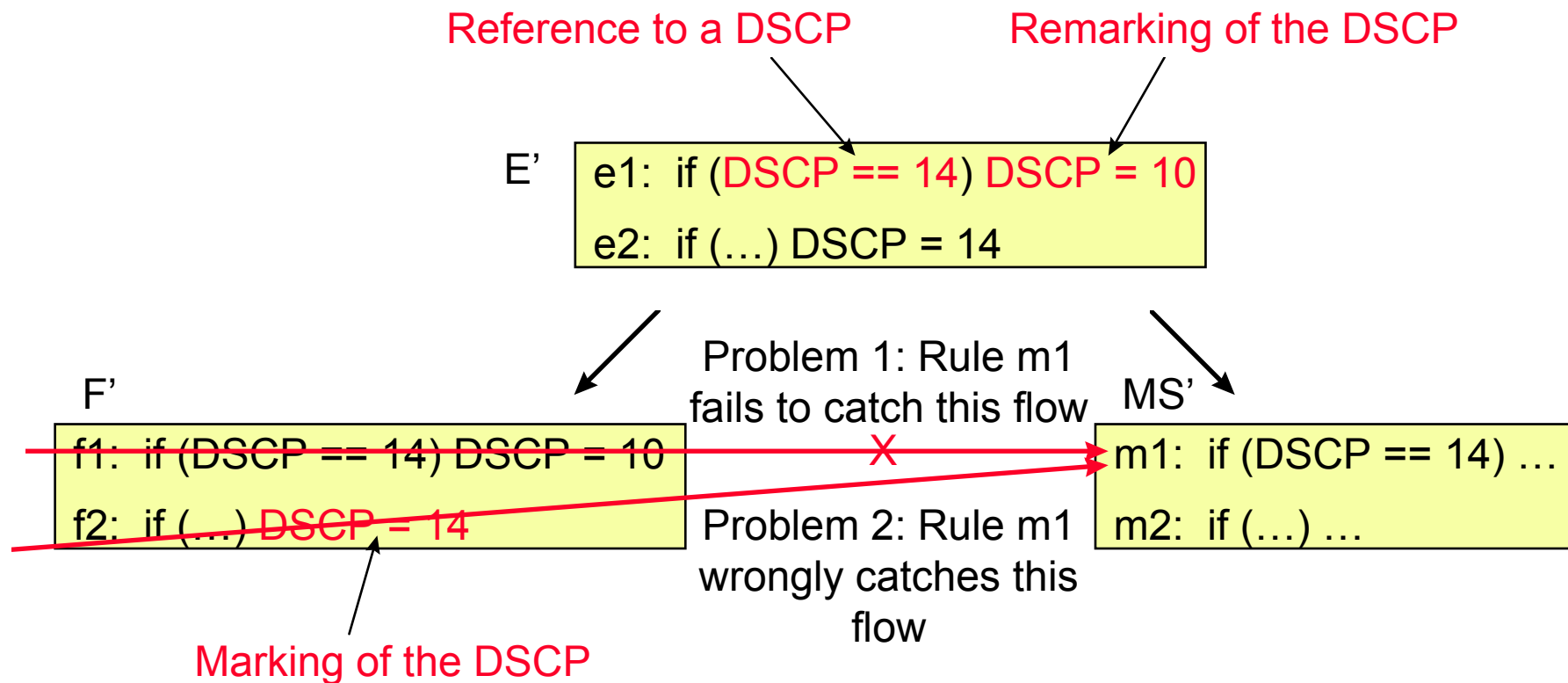
■ MS' =

```
{ if (DSCP == 10) {
    if (Information_rate < 1M bps) {} else { drop; }; } }
```

Restrictions on policy division

■ Restrictions on DSCP reference and marking

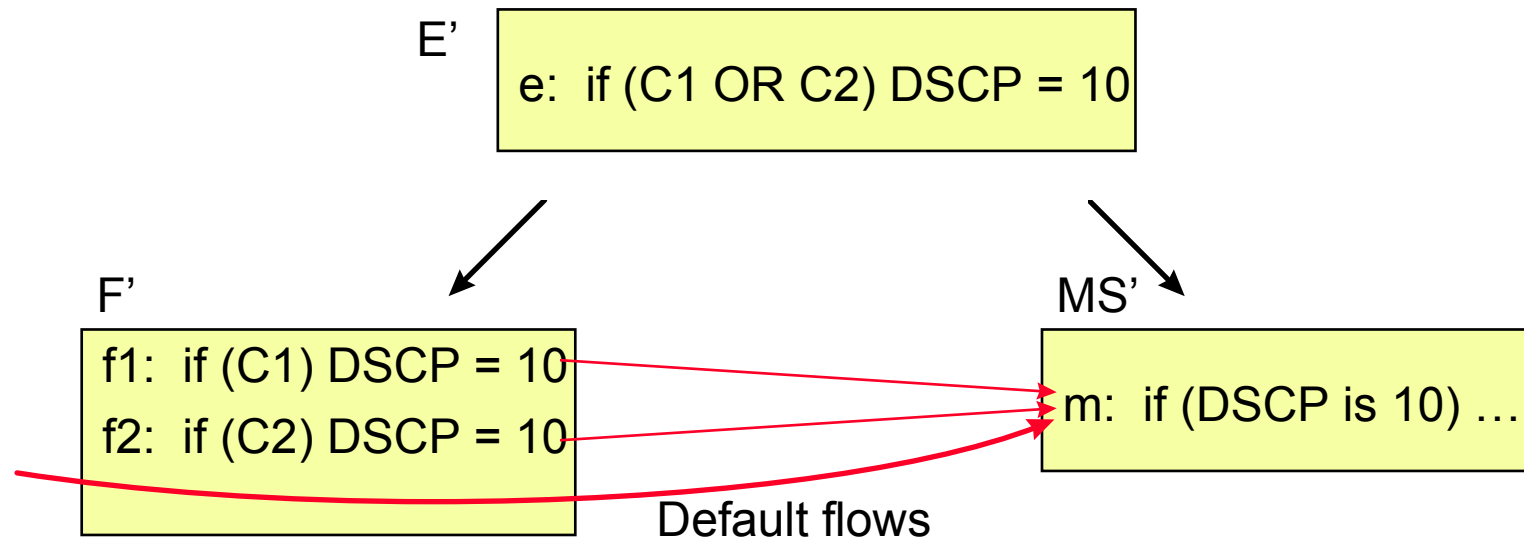
- ◆ If rules in the HL policy refer to a DSCP, and the rule remarks or another rule marks the DSCP, the naive transformation must be inhibited.



Restrictions on policy division (cont'd)

■ Restrictions on flow aggregation

- ◆ If a DSCP is used for identifying an aggregated flow, flows that are not caught by any rule in F' (called default flows) must be inhibited.



Policy fusion example: typical Diffserv policies

◆ This example is similar to the Case 1.

◆ **Inputs:** edge policy E1 and core policy C1

■ E1 = { ...,

```
if (Source_IP == ai) {  
  if (Information_rate < 1M bps) {DSCP = di;} else {drop;};  
}
```

Metering and marking actions

Conditions are different

...

■ C1 = { ...,

```
if (DSCP == di) {  
  Scheduling_algorithm = "WRR"; Min_BW = 512 kbps;  
}
```

Scheduling action

...

}.

◆ **Output:** Metering and scheduling policy MS1

■ MS1 = { ...,

```
if (Source_IP == ai) {  
  Scheduling_algorithm = "WRR"; Min_BW = 512 kbps;  
  if (Information_rate < 1M bps) {DSCP = di;} else {drop;};  
}
```

Scheduling action

Metering and marking actions

Restrictions in policy fusion

- The transformation in Case 2 is not restricted, but practically unacceptable because it generates too many rules.
- In the transformation in the Diffserv example (Case 1'), the following conditions are required not to increase the number of rules:
 - ◆ Each rule in HL policy E1 must mark or check a DSCP.
 - E.g., if (...) DSCP = ...; — marking action
if (DSCP == ...) ...; — checking condition
 - ◆ A default flow may not exist.
 - The following rule may have to be added:
if (true) drop;

3. A Method of policy division and fusion

A method of policy division and fusion

■ Restrictions (to avoid complexity)

- ◆ This method only applies to the edge and core policies.
- ◆ All the restrictions described before (may) apply.
- ◆ The core policy must have DSCP-only conditions (a BA classifier).
- ◆ See details for the paper.

A method of policy division and fusion (cont'd)

■ Outline of the algorithm

◆ Edge policy pass 1

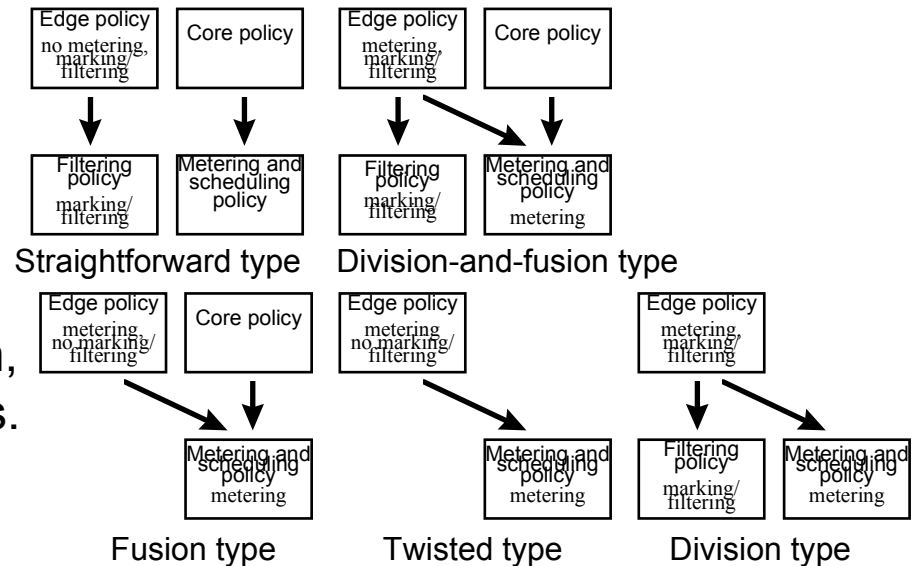
- The transformation type (TT) is determined.
 - Five TTs: straightforward, division-and-fusion, fusion, twisted, and division types.

◆ Core policy pass

- If the TT is the straightforward type, a metering and scheduling policy is generated from the core policy.
- Otherwise, a core policy table (DSCP-to-action mapping table) is created.

◆ Edge policy pass 2

- The HL policies are transformed into LL policies according to the TT.



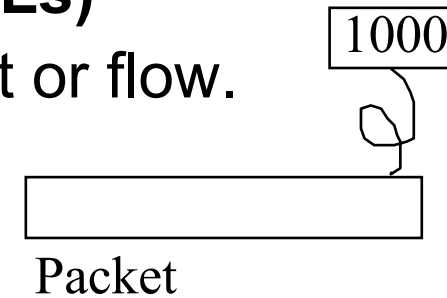
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4. Resolution of the problems

Resolution of the problems

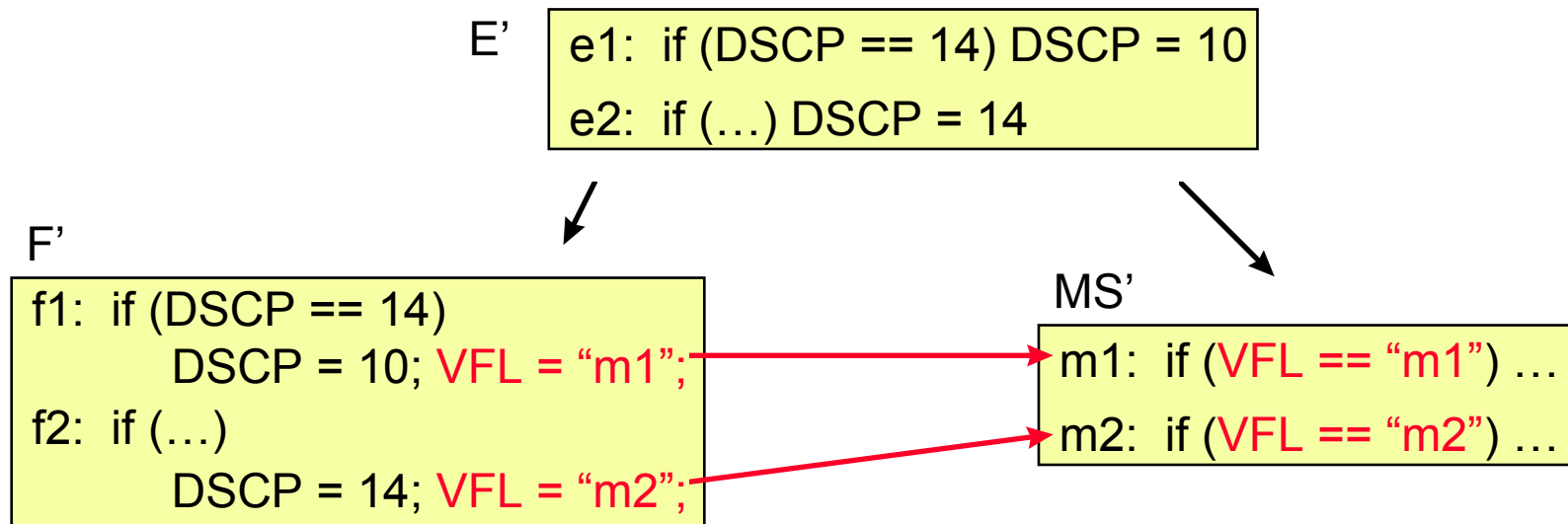
■ Introduction of virtual flow labels (VFLs)

- ◆ A VFL is a label attached to a packet or flow.
- ◆ A VFL is similar to a DSCP but it exists outside the packet.



■ Policy division using VFLs

- ◆ The restrictions can be eliminated by introducing VFLs in a policy division.





Conclusion

Conclusion

- **If the forms of HL policies are properly constrained, they can be translated into LL policies automatically by using policy division/fusion.**
- **However, policy division/fusion should be avoided if possible because**
 - ◆ the forms of HL policies are restricted, and
 - ◆ the transformation may be too much complicated.
- **The restrictions on policy division can be eliminated by introducing VFLs.**