

SNMP-based QoS Programming Interface MIB for Routers

(draft-kanada-diffserv-qospifmib-00.txt)

- **“Programming view”** (active network view) **is important for QoS control**
 - **The active networks:** Customizable, Downloading programs to nodes.
 - **Policy-based QoS control:** Customizing resources, Downloading policies (rule-based programs) to nodes — the first step towards AN.
 - We need *programs* for configuration, because the function is so complex.
 - Program semantics must be specified formally to be interoperable.
- **Design of the QoS MIB**
 - A step toward establishing programming methodology for active networks.
 - Features of the QoS MIB
 - **Rule Modularity** — very important for programming.
 - Each classifier, meter, or action is an if-then rule — separated by virtual flow labels.
 - The order of rules is not significant — the conditions are disjoint (no if-then-else).
 - **Classification of scheduling algorithms:** 1) First-in first-out (FIFO) scheduling, 2) Priority scheduling, 3) Packet-fair scheduling, 4) Byte-fair scheduling, 5) Bounded byte-fair scheduling
 - **Classification of dropping algorithms:** 1) Dropping all, 2) Tail dropping (non-early dropping), 3) Random early dropping (RED/WRED), 4) Deterministic early dropping (DED/WDED)
- **Problems and solutions in current programming interfaces (PIFs)**
 - Typical PIFs for QoS control: 1) SNMP & MIB, 2) COPS & PIB, 3) API
 - Problems in PIFs by MIB (& PIB): Unsuitable for representing program semantics
 - Mismatching of syntactic structures and of unit or operation
 - Possible solutions
 - To design a rule-based programming language for the interface.
 - This language may be implemented using any protocol.
 - The language semantics must be mapped to the protocol usage formally.
 - Or, the definition of a protocol must embed a language definition.
 - A new method of specifying protocols is required.